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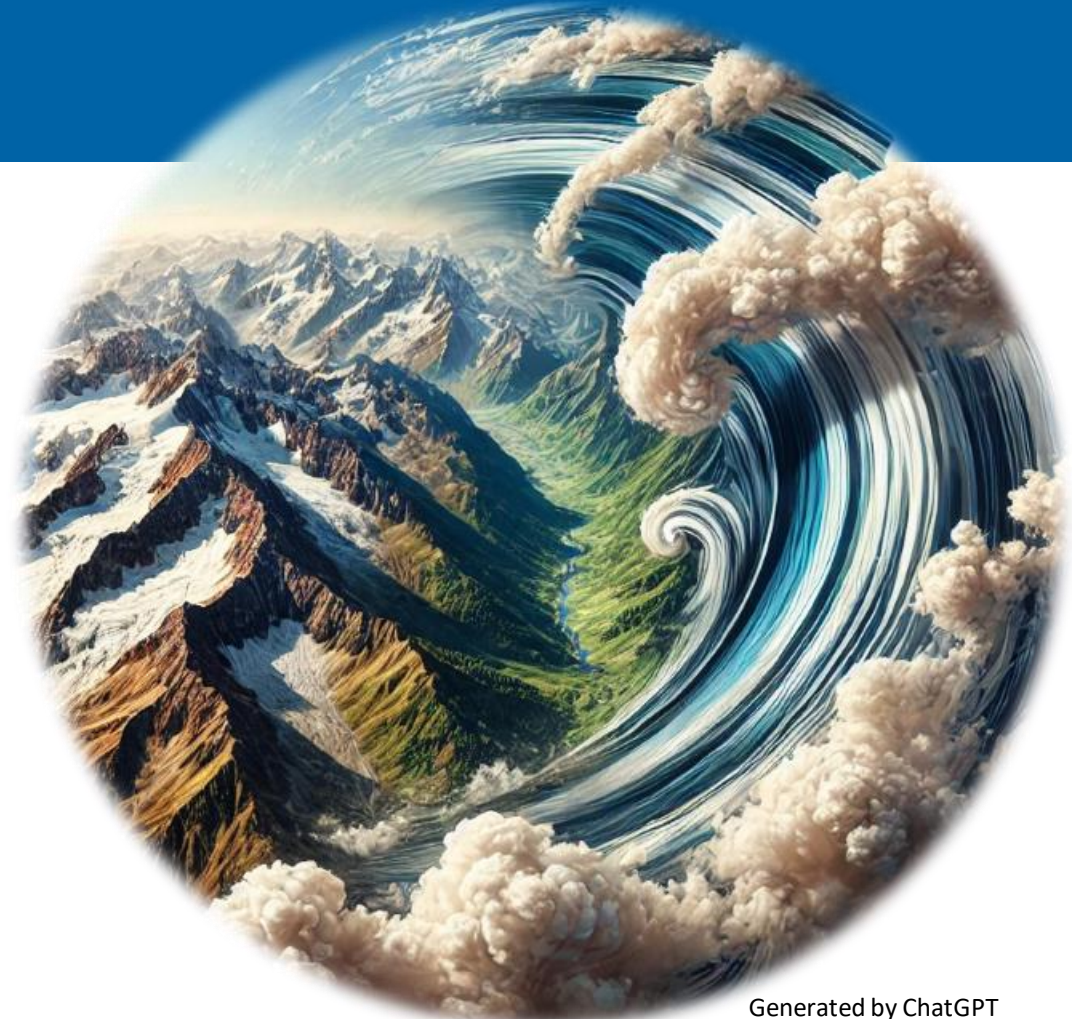


GeoSphere
Austria

Assimilation of T2m with Hybrid-3DEnVar over The Alps in AROME-Austria

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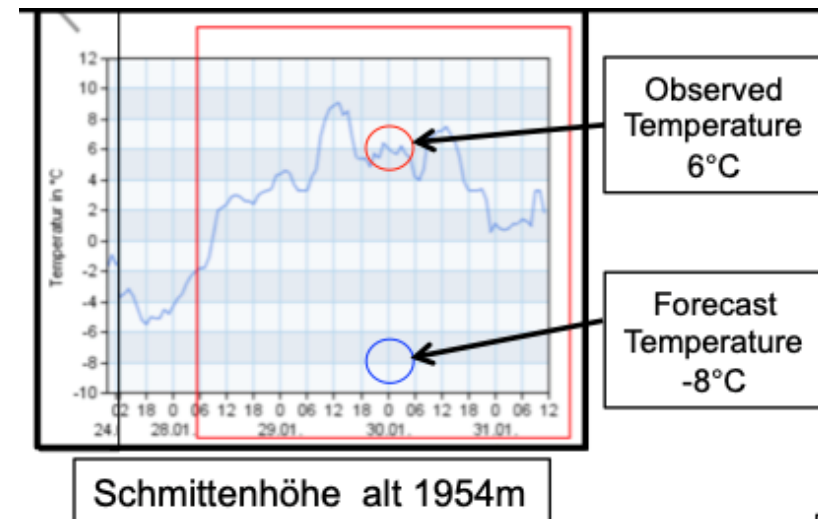


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Motivation

- Data assimilation (DA) provides initial conditions to the NWP model
 - GeoSphere is currently using the 3-Dimensional Variational (3DVar, *Courtier et al., 1998*) for DA
- Making use of [GeoSphere's Convection-permitting Limited-Area Ensemble Forecasting \(C-LAEF, Wastl et al., 2021\)](#)
 - CLAEF consists 16 members + 1 control
 - at 2.5 km
- We want to improve the T2m forecast
 - Correctly forecasting T2m is hard in complex terrain
 - Specifically in anticyclonic conditions

60-hr lead time valid at 00 UTC 30 Jan 2024



Data Assimilation

- DA combines past forecasts (background) and observations weighted by the inverse of respective errors
- GeoSphere Austria uses the 3DVar method for DA

(squared deviation of background from model state)

$$\mathbf{J}(\mathbf{x}) = \frac{1}{2}(\mathbf{x} - \mathbf{x}_b)^T \mathbf{B}^{-1} (\mathbf{x} - \mathbf{x}_b) + \frac{1}{2}[\mathbf{y}_o - \mathbf{H}(\mathbf{x})]^T \mathbf{R}^{-1} [\mathbf{y}_o - \mathbf{H}(\mathbf{x})]$$

(squared deviation of observations from model state)

- Precise representation of forecast errors (**B**) is crucial for accurate ICs

\mathbf{x} = model state vector

\mathbf{x}_b = background state vector

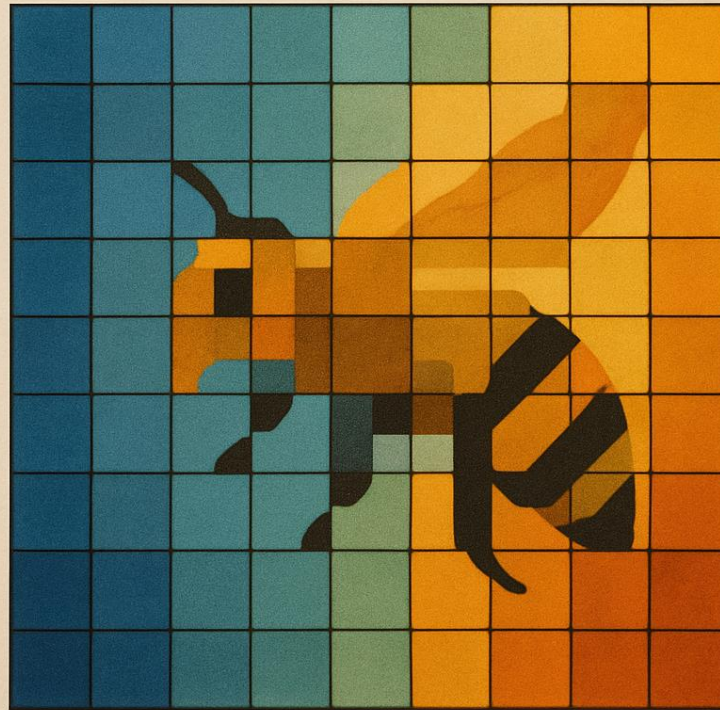
\mathbf{y}_o = observation state vector

\mathbf{H} = forward observation operator

\mathbf{B} = background error covariance matrix

\mathbf{R} = observation error covariance matrix

Matrix

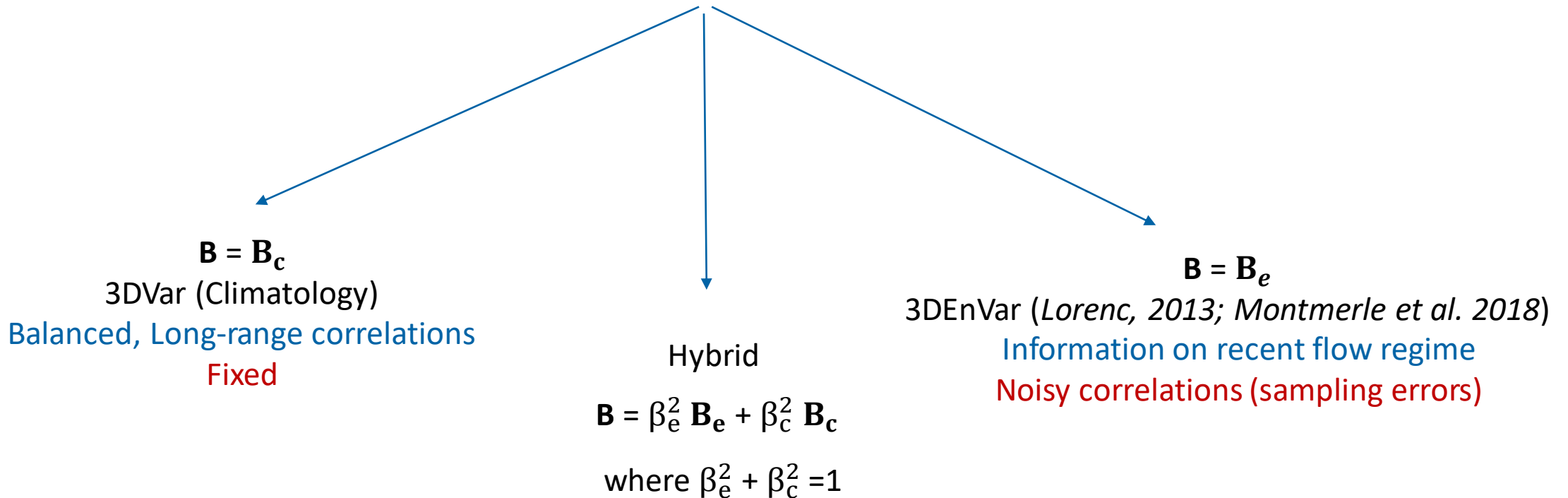


a picture of a bee in the form of a matrix

Ways of estimating B

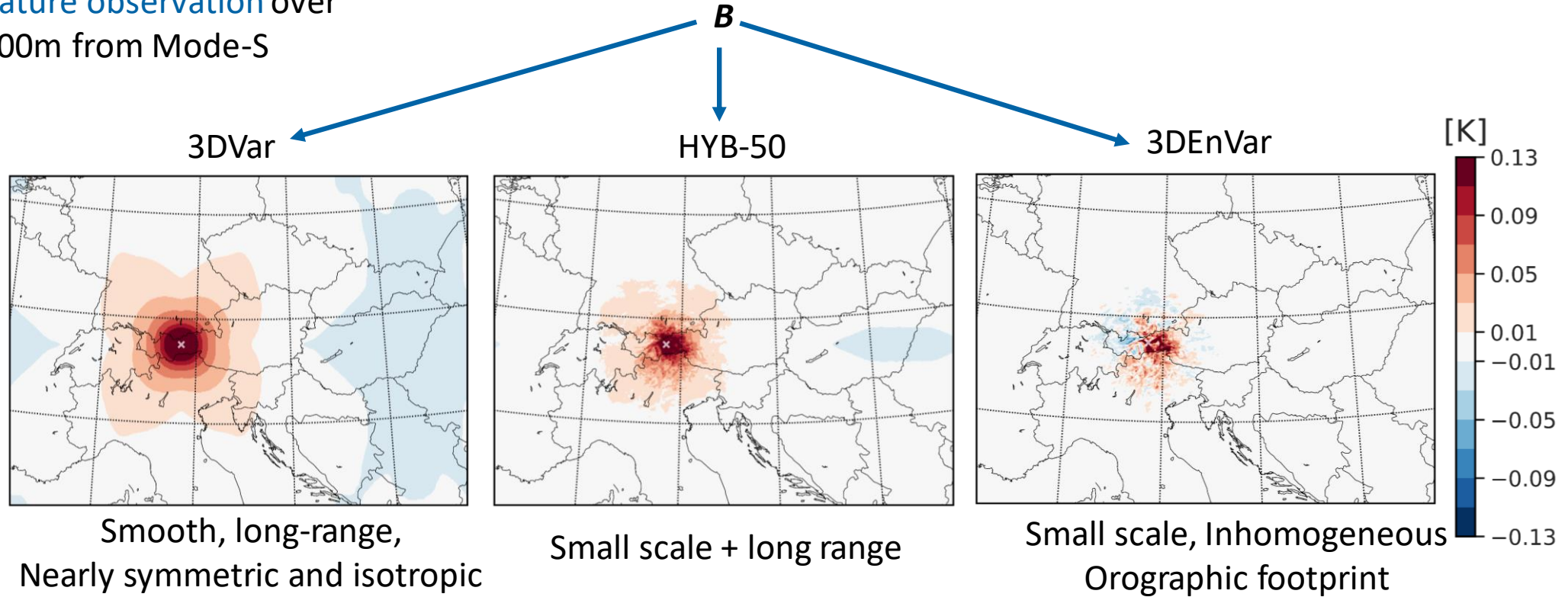
$$\mathbf{B} = \begin{pmatrix} \sigma_1^2 & cov(\sigma_2\sigma_1) & \dots \\ cov(\sigma_1\sigma_2) & \sigma_2^2 & \\ \vdots & & \ddots \\ cov(\sigma_1\sigma_m) & \dots & \sigma_m^2 \end{pmatrix}$$

- Symmetric positive semi-definite 10^{15}
- variances on the diagonal
- covariances (correlations) at off-diagonal



Different B provide different increments (ICs – background)

- a single temperature observation over Innsbruck at 1600m from Mode-S

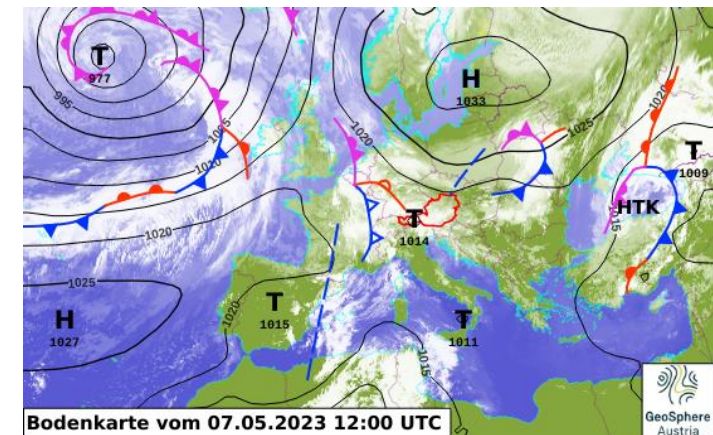
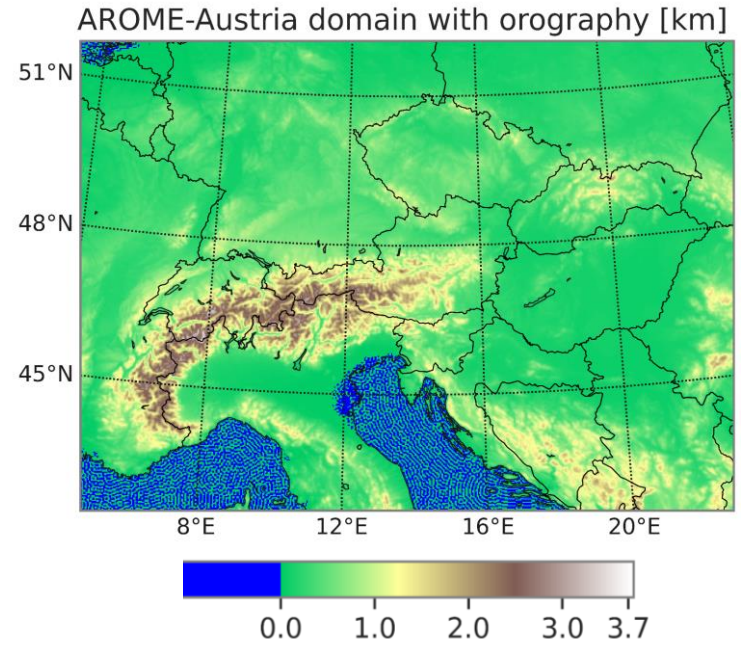


Nearby valleys and mountain tops can have different weather, leading to different degrees of small-scale correlation, even **negative correlations** in atmospheric variables.

Does assimilation of T2m with Hybrid-3DEnVar
improve the forecast, particularly over Alpine terrain?

AROME-Austria

- Convective-scale at 2.5 km grid spacing
- Assumed to allow deep convection
- 600x432x90 grid-points
- 50-member ensemble from C-LAEF at 2.5 km.
- Test case: 1200 UTC, 07-05-2023

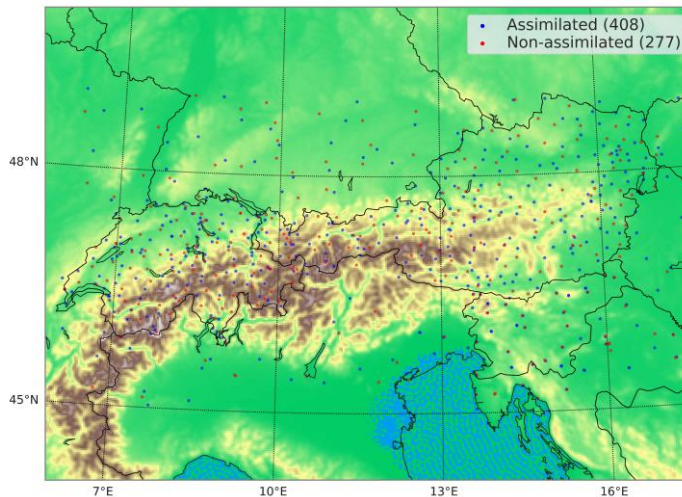


Method

- Experiments
 - 3DVar (B_c)
 - HYB-50 $0.5(B_c + B_e)$
 - 3DEnVar (B_e)

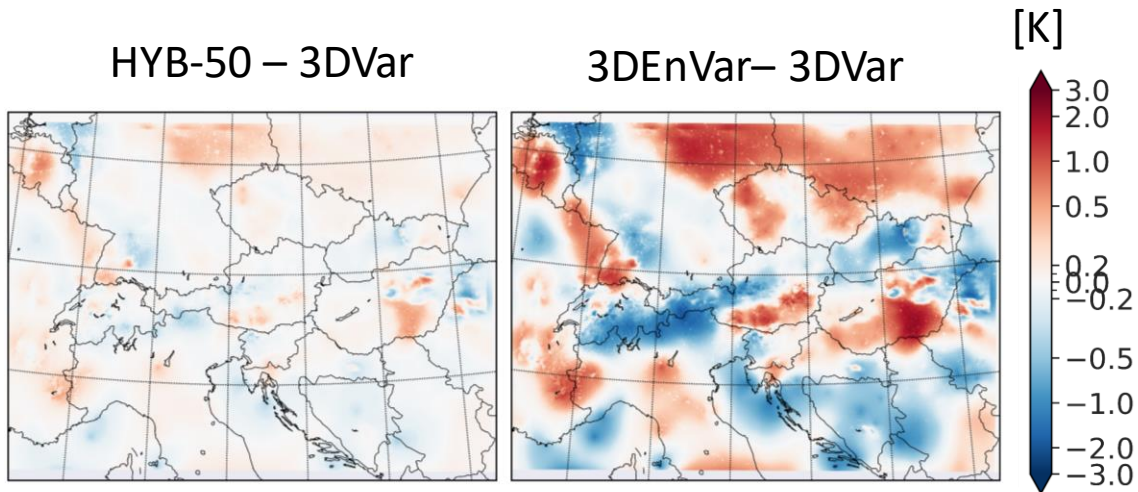
- Verification

$$RMSE = \sqrt{\frac{1}{n} \sum_{i=1}^n (F_i - O_i)^2}$$



- 408 stations are assimilated
- 277 stations for verification

Evaluation of T2m forecast at 0-hr lead time

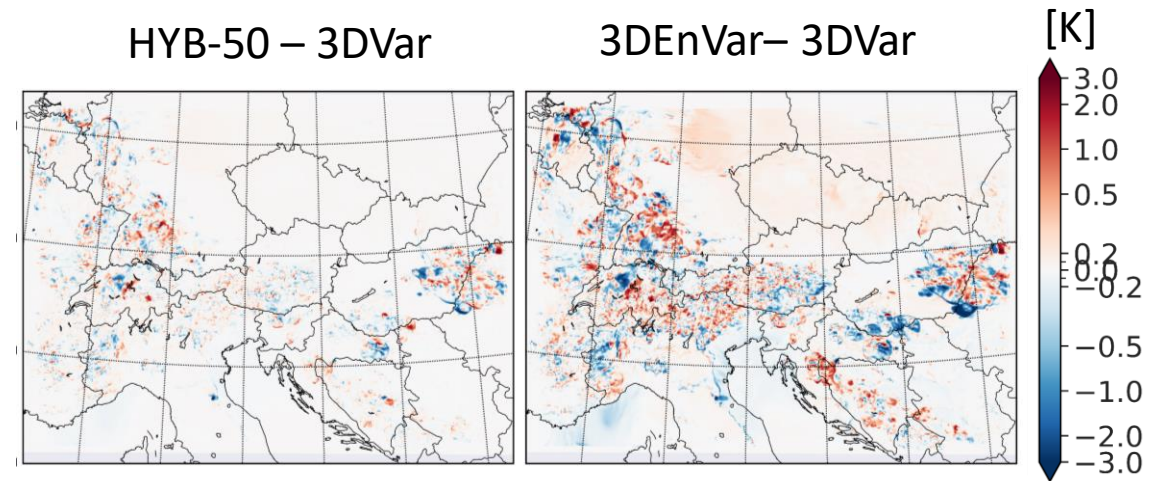


- Substantial differences in the forecasts

No-assimilation	3DVar	HYB-50	3DEnVar
2.20	1.92	1.93	2.06

- Assimilating T2m **improves the 0-hr forecast** in all experiments

Evaluation at 3hr lead time



Differences are still present at a 3-hr lead time and are adjusted as the model evolves

Evaluation at 3hr lead time

Valley ($z < 800$ m)

Mid-altitude ($z = 1000$ to 2000 m)

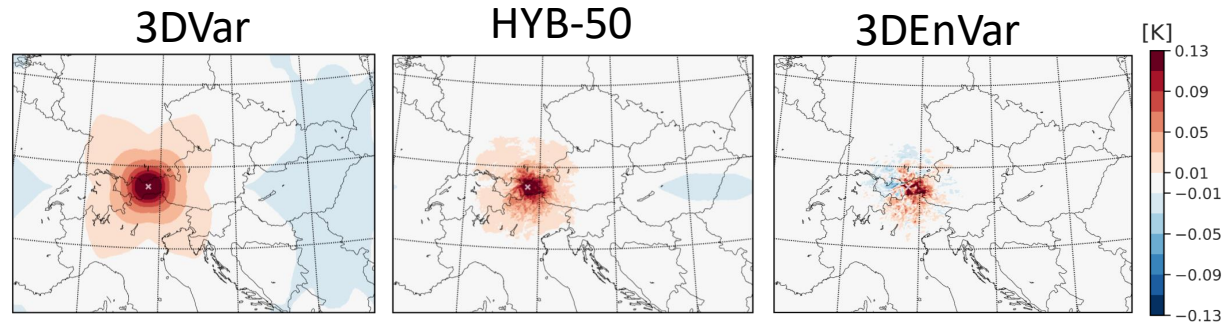
Mountain ($z > 2000$ m)

Experiment	$z < 800$ m (valley)	$z = 1000$ - 2000 m (mid-altitude)	$z > 2000$ m (mountain)
3DVar	1.90	4.37	2.50
HYB-50	1.92	4.33	2.49
3DEnVar	1.89	4.30	2.43

Forecast from **HYB-50 and 3DEnVar improved** compared to 3DVar

Conclusions

- Successful use of C-LAEF in 3DVar data assimilation while assimilating T2m in AROME-Austria.
- 3DEnVar and HYB-50 can be a suitable alternative over 3DVar in the Alps.



- T2m Forecast from 3DEnVar improves compared to 3DVar. HYB-50 slightly degrade forecast in valleys.

Experiment	$z < 800$ m (valley)	$z = 1000 - 2000$ m (mid-altitude)	$z > 2000$ m (mountain)
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